



ICEPOD

TEAM ICEPOD: Robin Bell, Nick Frearson, Kirsty Tinto, Chris Zappa, Chris Bertinato, Tej Dhakal, Scott Brown, Ling Ling Dong, Indrani Das, Mike Wolovick, Margie Turrin, Jim DeTemple

With Tremendous Support From NYANG
especially Major Josh Hicks, Senior Master Sargent Joe Deamer

Lamont Doherty Earth Observatory
Columbia University





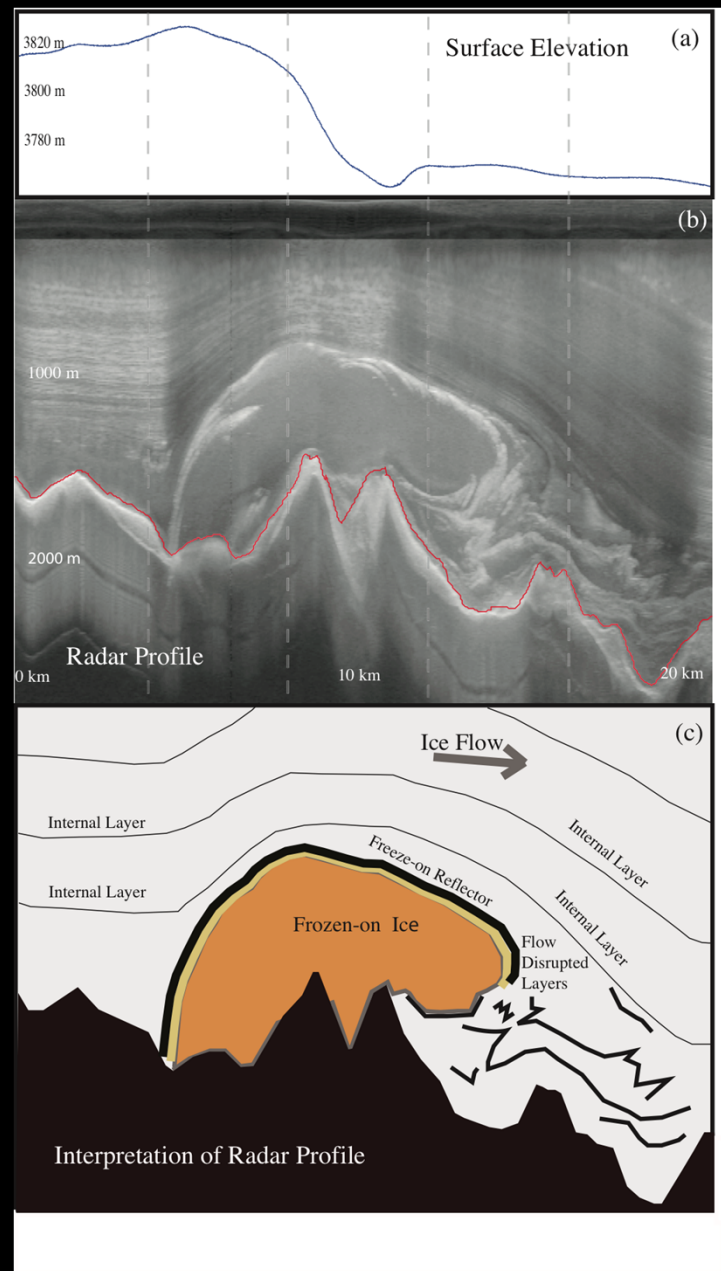
Lamont-Doherty Earth Observatory
COLUMBIA UNIVERSITY | EARTH INSTITUTE



INTERNATIONAL 2007-2008
POLAR YEAR



Up to 1000m
Thick----50%
of the Ice
Sheet



Remote Field Camps







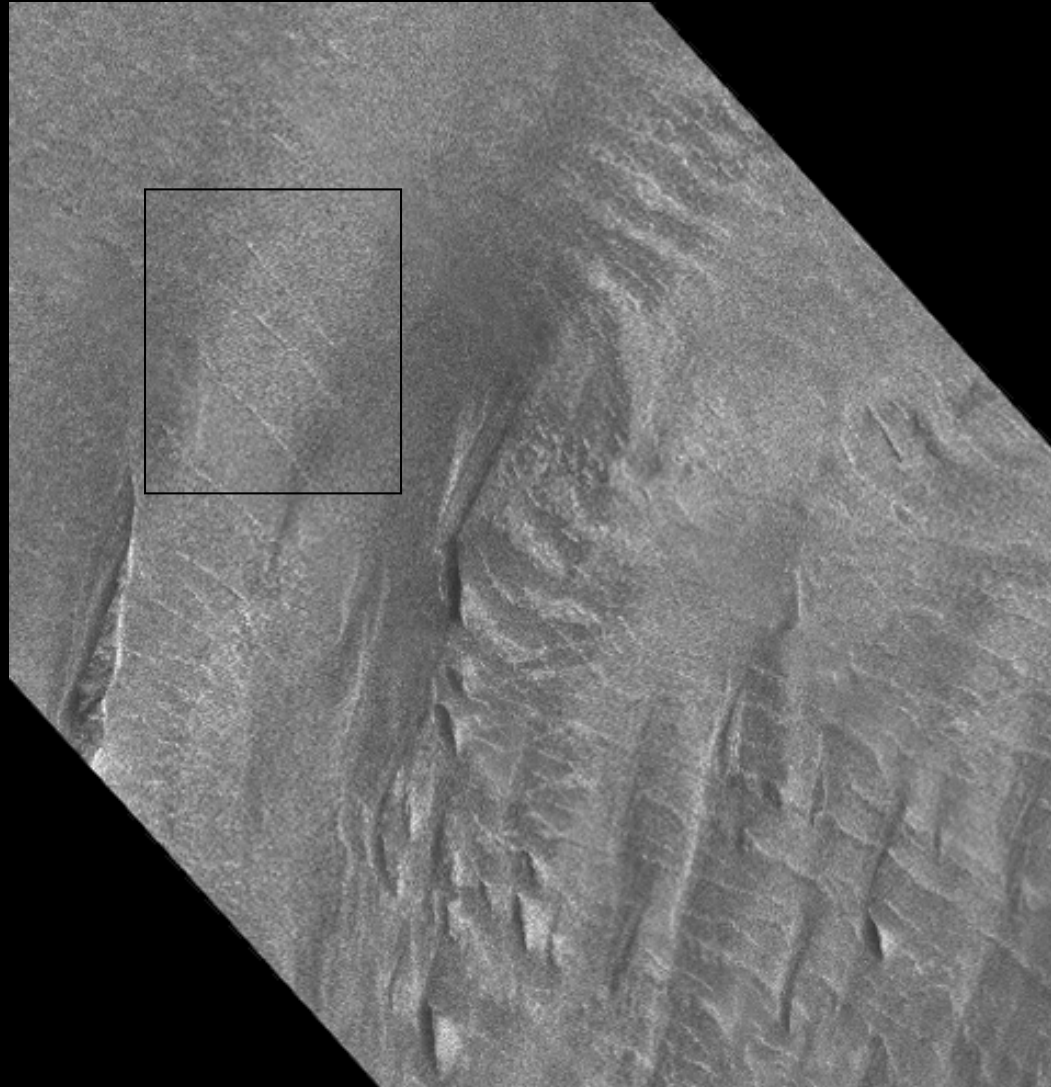




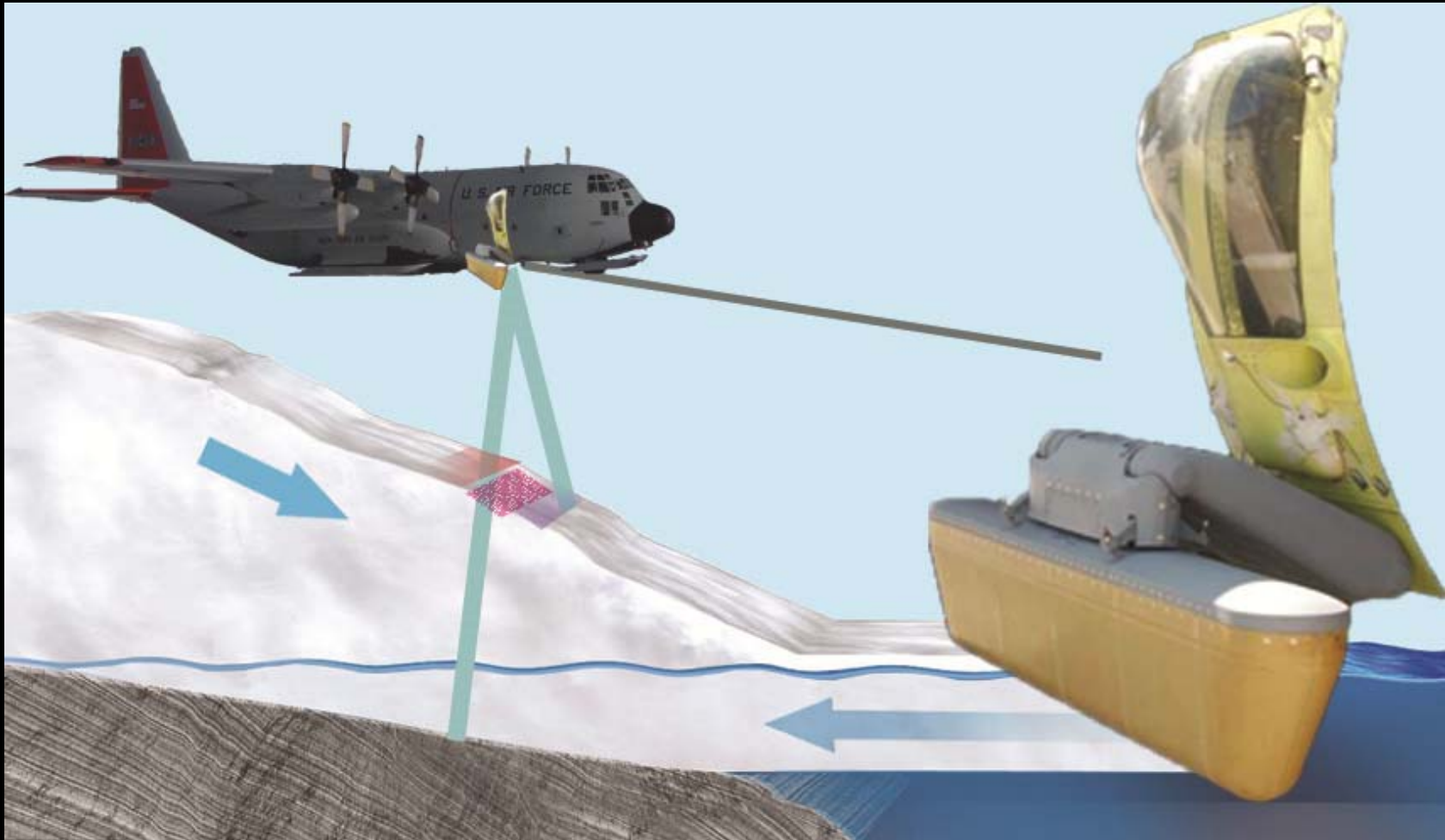
Crevasse Detection Radar (CDR)



CDR Image of Tres Hermanas (3 Sisters) Crevasses



Recovery Act Funding Early Pod Design



IcePod

Recovery Act Funding

Goal Instruments, Data and Platform for
Community Use through Piggyback Missions and
Dedicated Flights



Icepod

- Pod Delivered January 7, 2013
- Flight Certified January 29, 2013
- Field Operation Test April 2013 - Greenland
- Instrument Test July/August 2013 – Greenland
- Commission Antarctica 2014

Icepod

- Operational Modes
 - Piggyback Missions
 - 10% regular missions Antarctica & Greenland
 - Dedicated Investigator Lead Missions
 - Recovery Catchment, Ross Ice Shelf
 - Instrument Development Platform
 - Air sampling, lave tube imaging

A Troop Door



An Arm



An LC-130



A Data Acquisition Rack



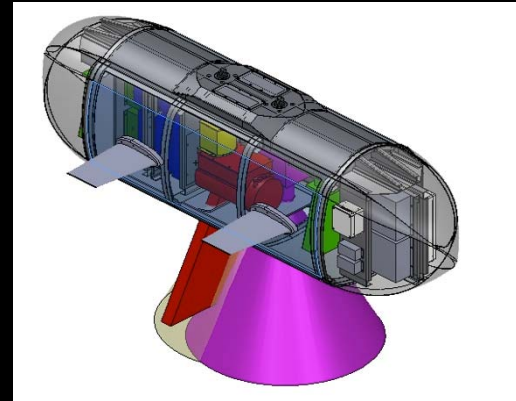
A Sensor Pod



A Skilled Team Including the Guard

IcePod Instrumentation

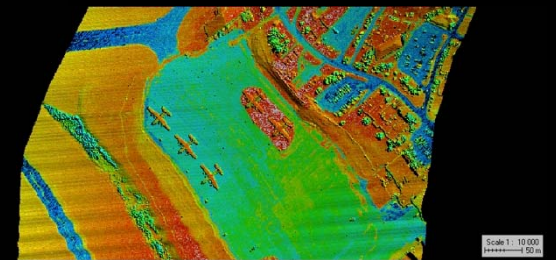
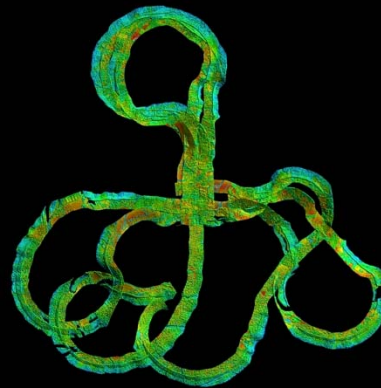
- Optical Instruments
 - IR Camera
 - Pyrometer
 - High Res Vis Wave Camera
 - Scanning Laser
- Radar
 - Deep Ice
 - Shallow Ice [100m]
- Georeference
 - GPS
 - IMU

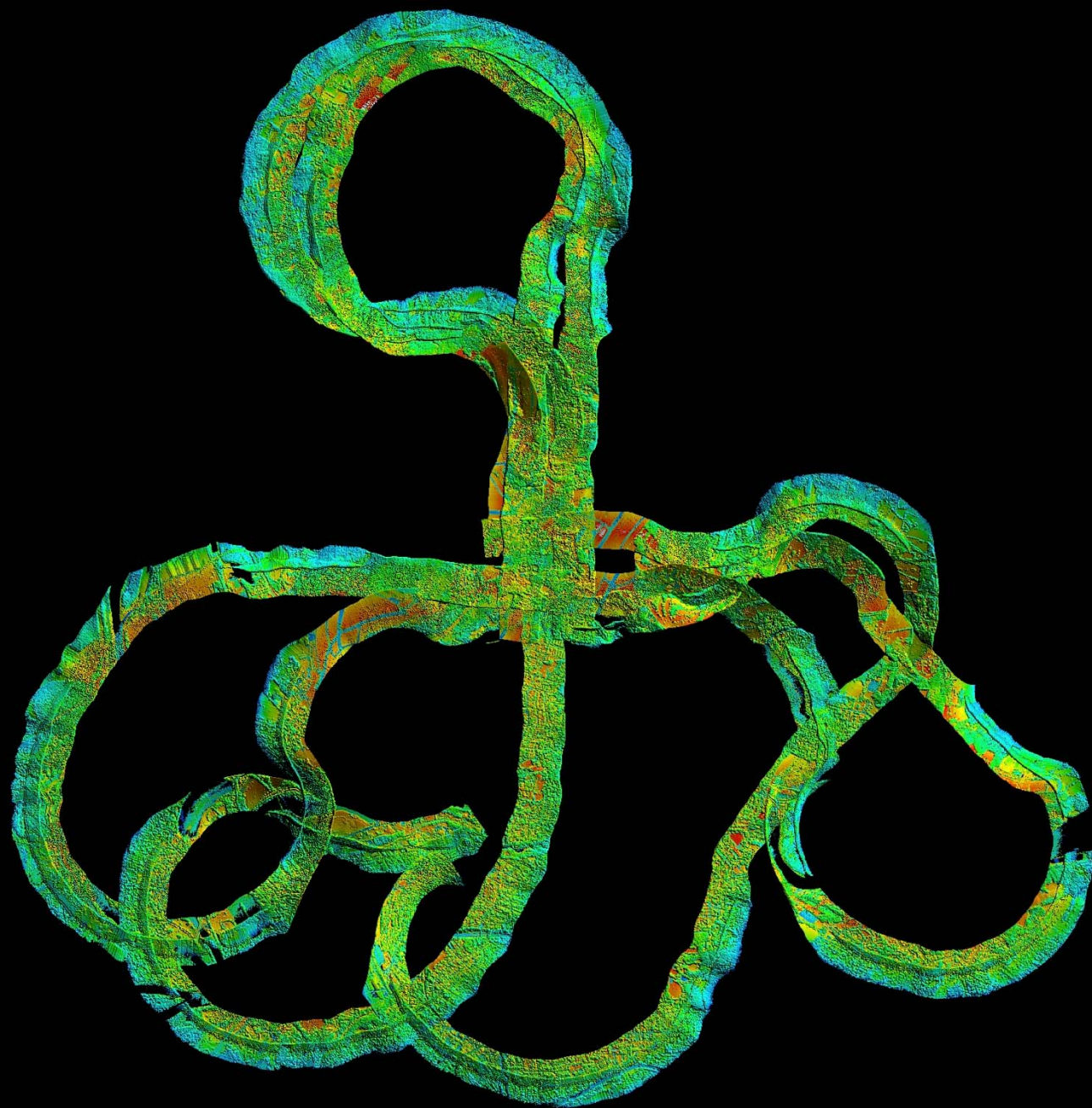


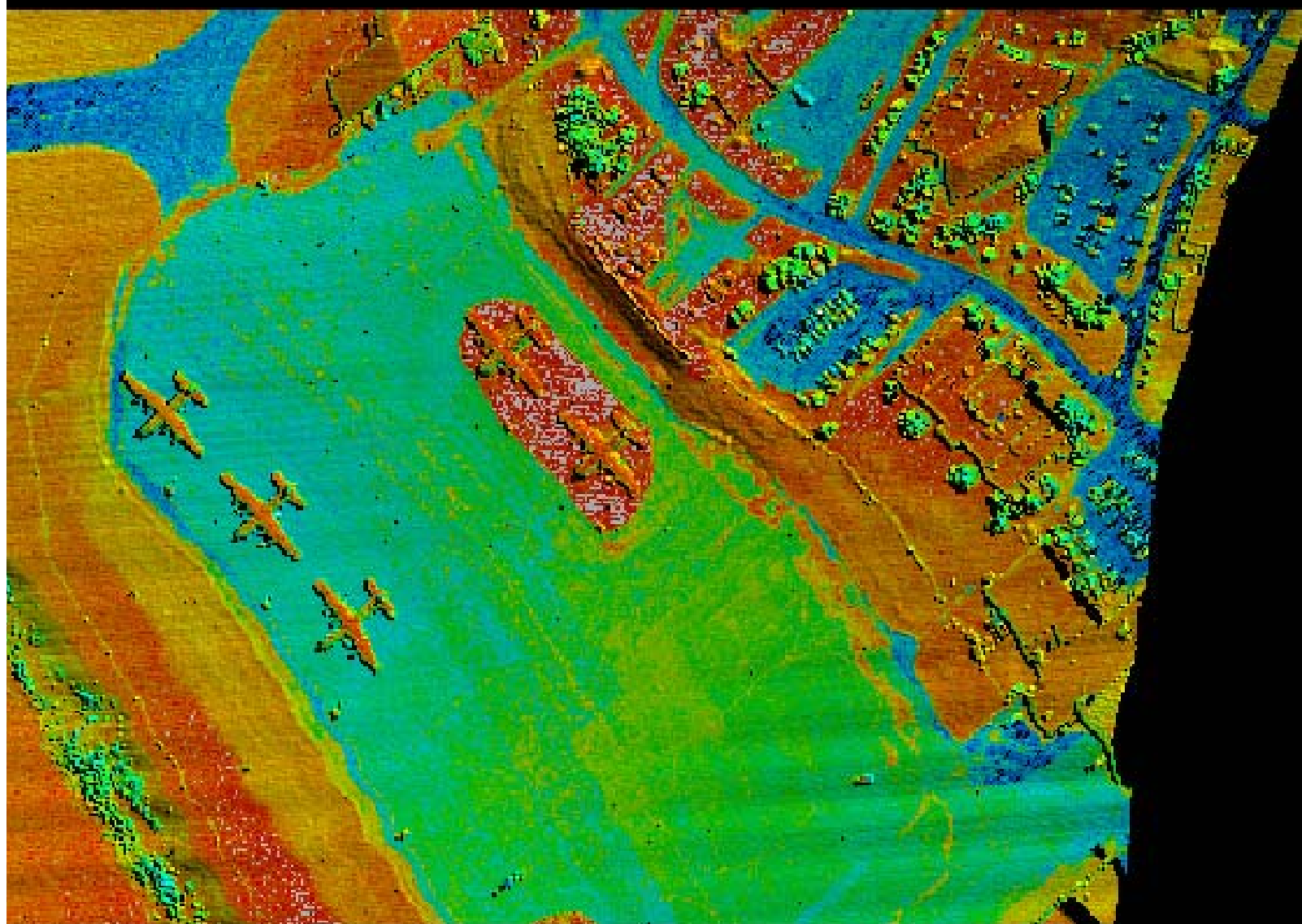
IcePod Instrumentation

Laser:

- Type: RIEGL VQ-580 Swath scanning laser
- Range Resolution: 2mm Lidar + ~10cm GPS
- Swath width: ~3,000 ft at 3,000 ft altitude
- Applications: Surface Profiling/Glacier Mapping
- Max scanning altitude: 3,950 AGL feet







Scale 1 : 10 000
|-----| 50 m

IcePod Instrumentation

Infrared Camera

Type: Sofradir IRE640L LWIR: 7-9.5um

Accuracy: < 20 mK NEDT

640 x 512 pixels 100 frames/second

Rotary Sterling Cooler [i.e does not need external cooling]

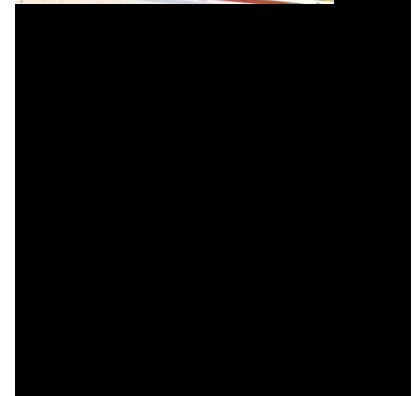
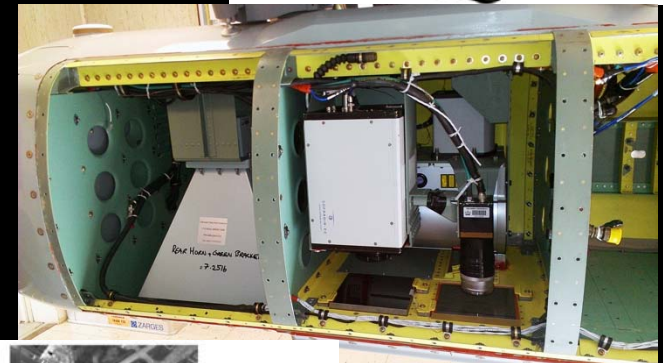
Applications: Thermography

Swath width: 350 m at 1,000m

Resolution: 50 cm

Specifications:

- Temp: -40° C to $+55^{\circ}$
- Altitude: 30,000 ft
- Supply: +24Vdc
- Weight: 12lb





IcePod Instrumentation

Sky Pyrometer

Type: Heitronics KT-15

Response: 0.6 ° C

Applications: Surface Reflection Correction

FOV: 3° upward-looking

Specifications:

- -40° C to 60° C
- 30,000 feet MSL
- Supply: +28Vdc
- Weight: 2.5lb
- Dimensions: 6" x 2" x 2"



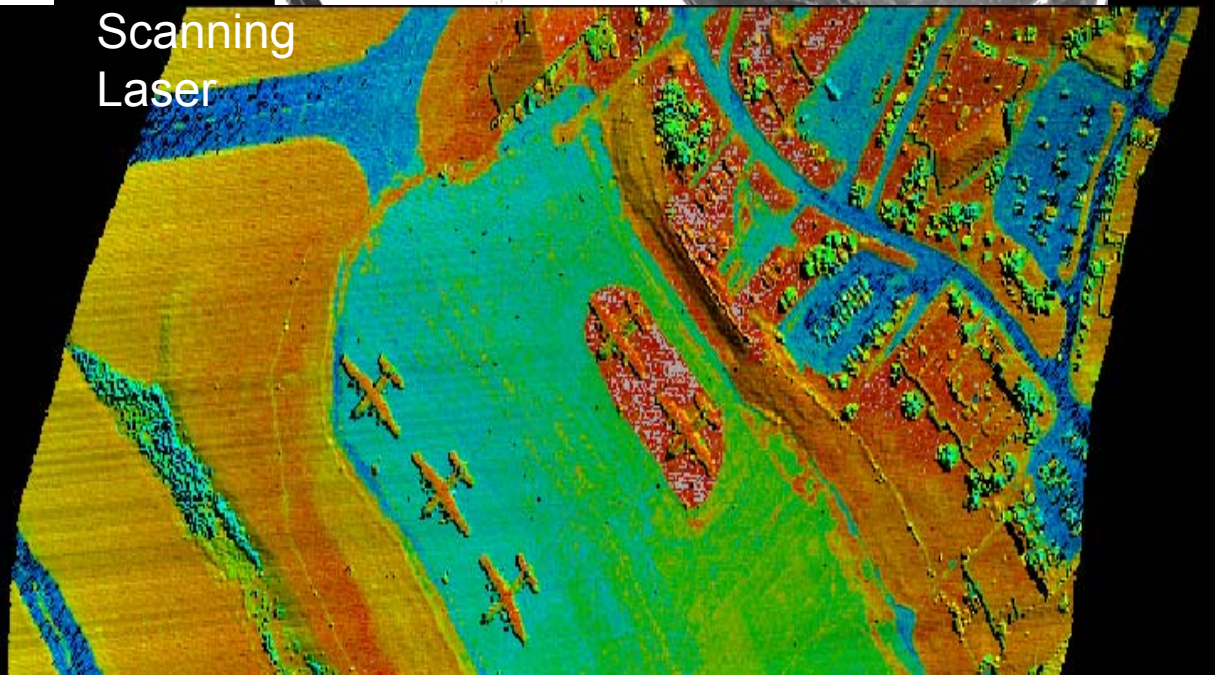
Visible wave



Infra-Red



Scanning
Laser



IcePod Instrumentation

Visual Camera

Type: Imperx Bobcat 6620

29Mpixel; 6600 x 4400; 12-bit

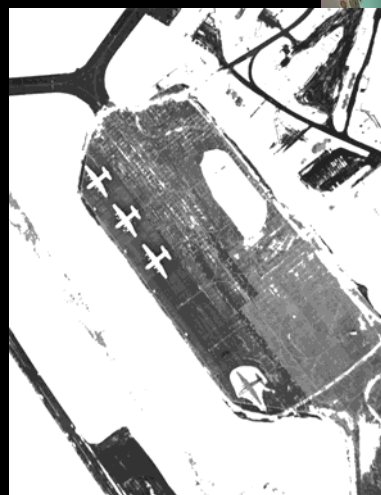
Accuracy: 20cm at 1,000m altitude

Swath width: 1,200 m at 1,000m

Applications: Photogrammetry

Specifications:

- -40° C to $+80^{\circ}$ C
- 30,000 feet MSL
- 2.5lb
- +12Vdc





IcePod Instrumentation

Deep Ice Radar

Type:

- High-Power Coherent Pulsed Radar
- Transmitter: 800W per channel; 2 channels
- Center Frequency = 188MHz
Bandwidth = 60MHz
- 1us and 10us interleaved chirp signals

Depth Resolution:

- 2.8m

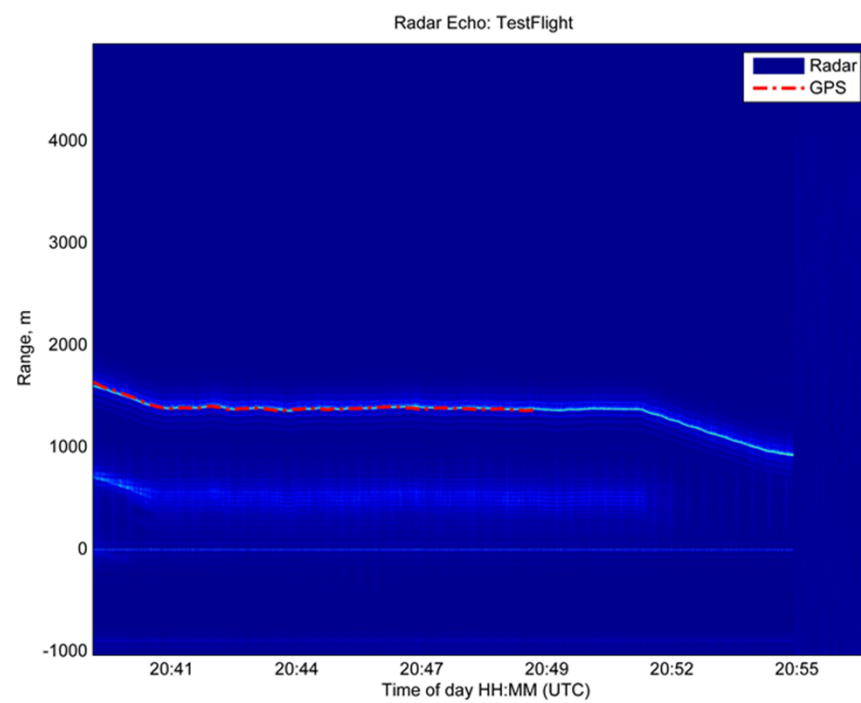
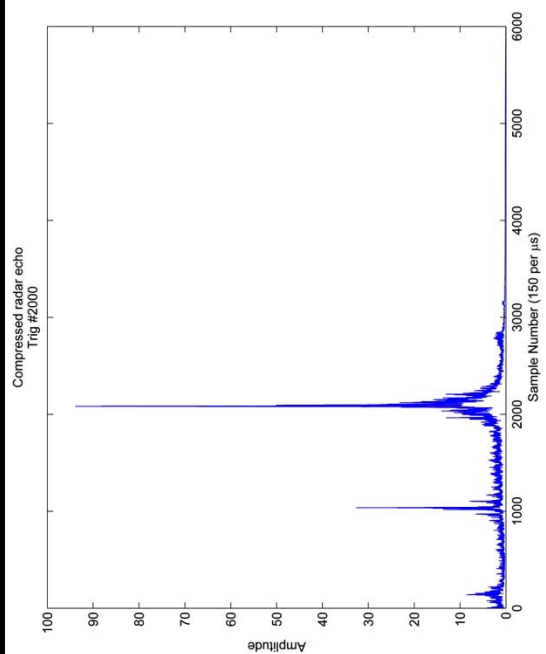
Applications:

- ice thickness, internal structure, bedrock mapping

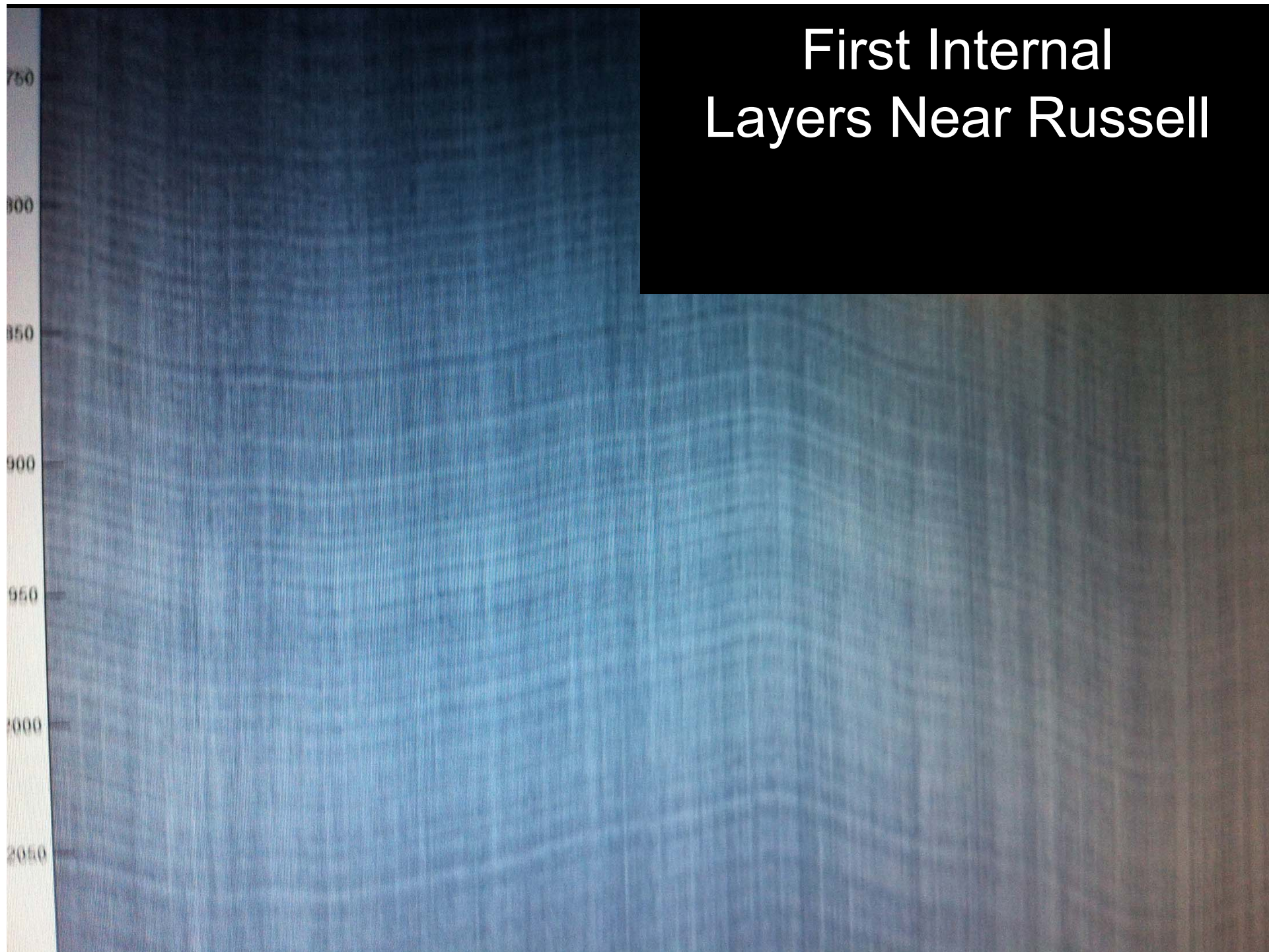
Specifications:

- Dimensions: 18" x 18" x 18" Weight: 83lb





First Internal Layers Near Russell



IcePod Instrumentation

Positioning IMU and GPS

Type: L1/L2 GPS GLONASS

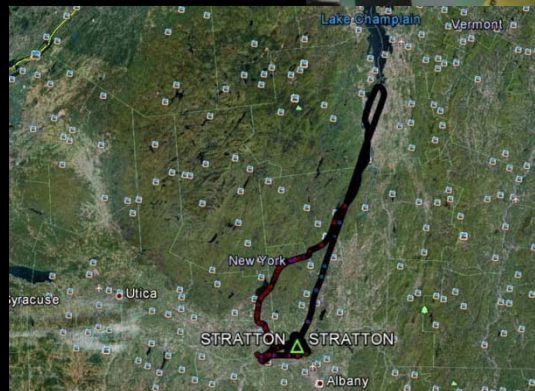
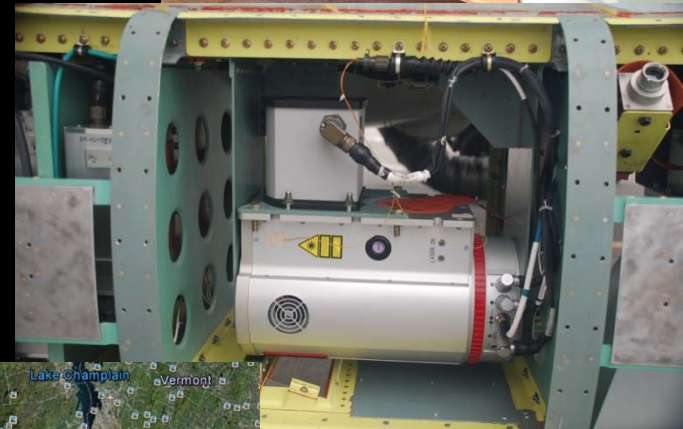
IMU: LN-200, Fiber-Optic Gyros

Accuracy: 10 cm

Applications: Position and attitude

Specifications:

- GPS:
 - 10lb
 - +28Vdc
 - 10" x 8" x 3"
- IMU
 - 8lb
 - +28Vdc
 - 7" x 5" x 5"



IcePod Instrumentation

Shallow Ice Radar [SIR]

Type:

- FMCW
- Transmitter Power = $\sim 10\text{W}$ for Firn Ice and $< 1\text{W}$ for sea-ice
- Center Frequency = 2GHz
- Bandwidth = 600MHz

Range Resolution:

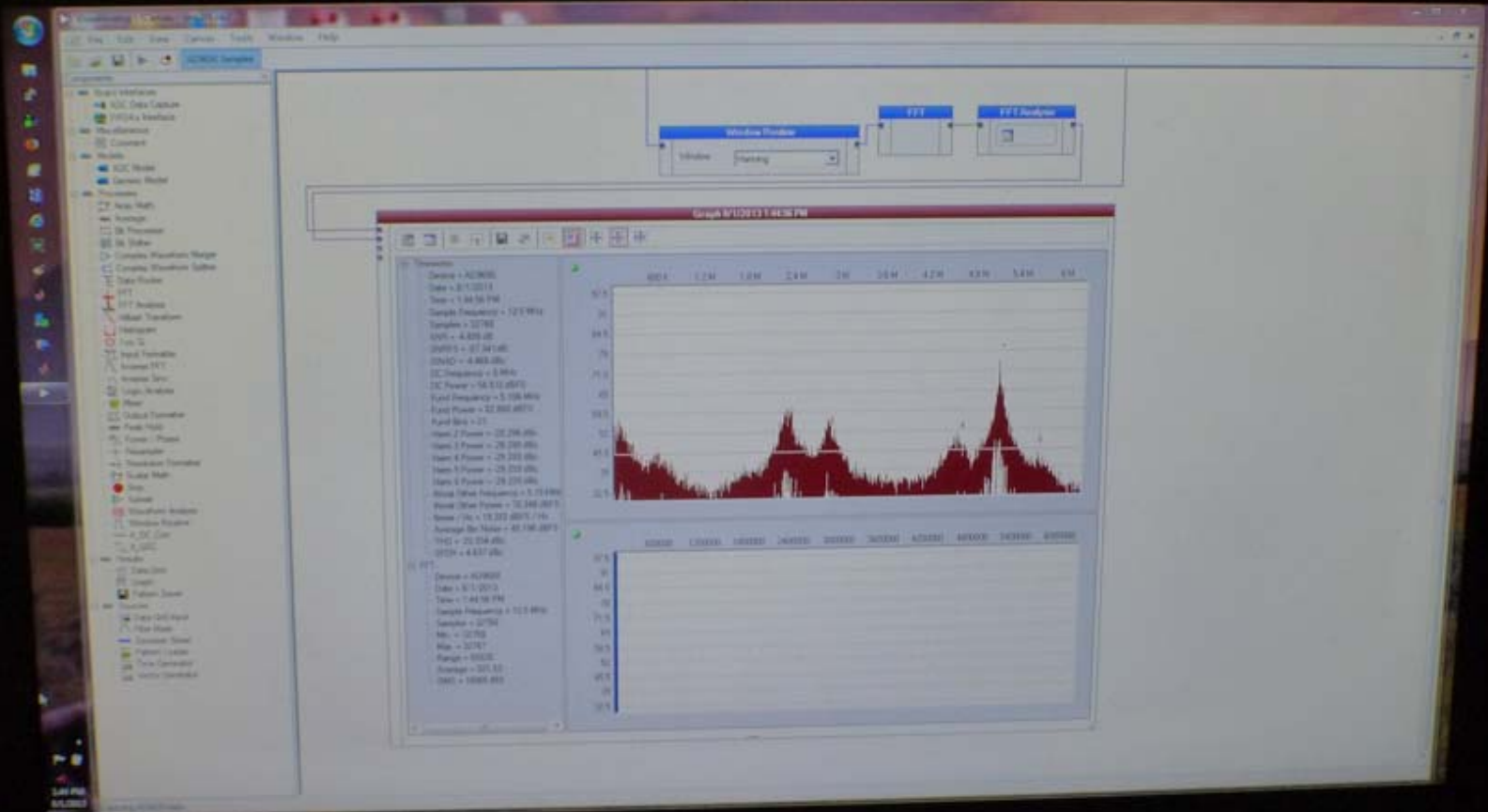
- 25 cm

Applications:

- Sea-Ice: Snow Pack, Ice Depth
- Firn internal structure to 100m



Shallow Ice Radar Returns



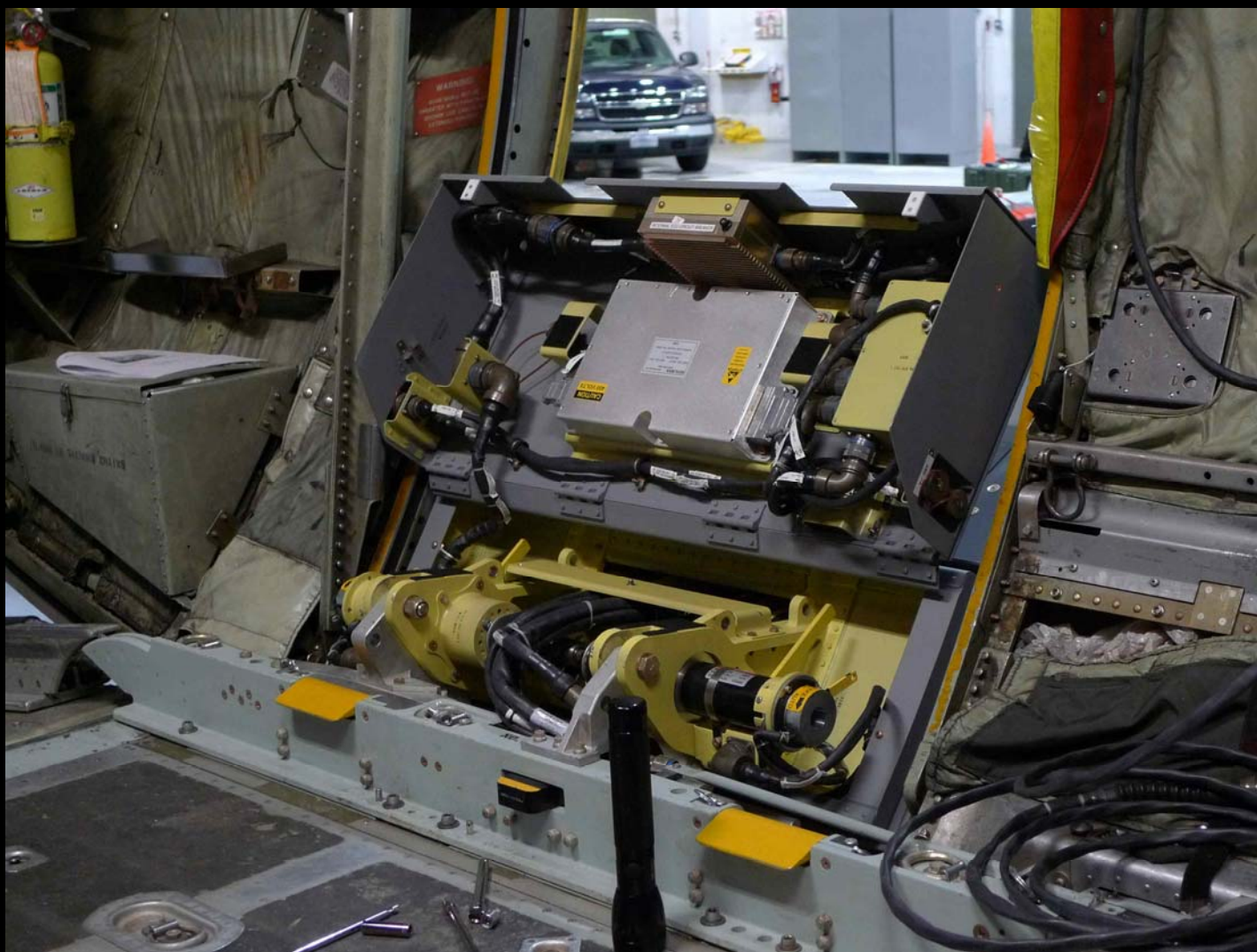
Lab Installation to Flight Ready in 2 days



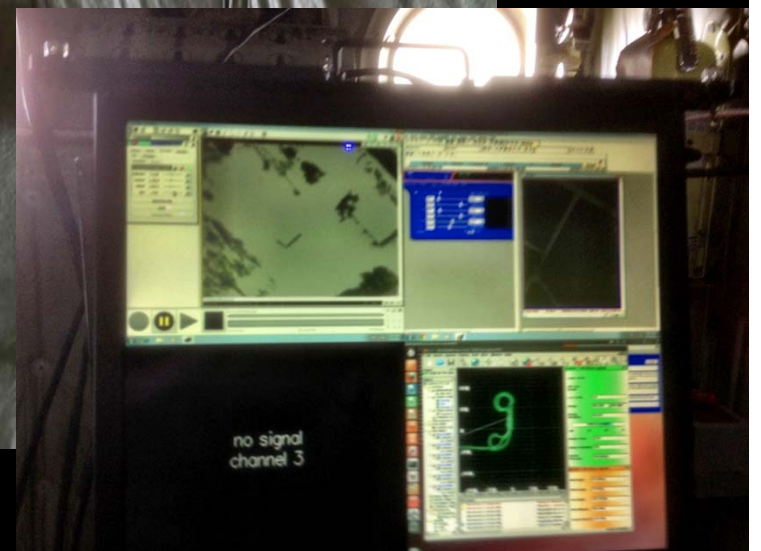
1. Disassemble and pack system: ~3h
2. Unpack and install system: ~4h
3. Test System: ~2h









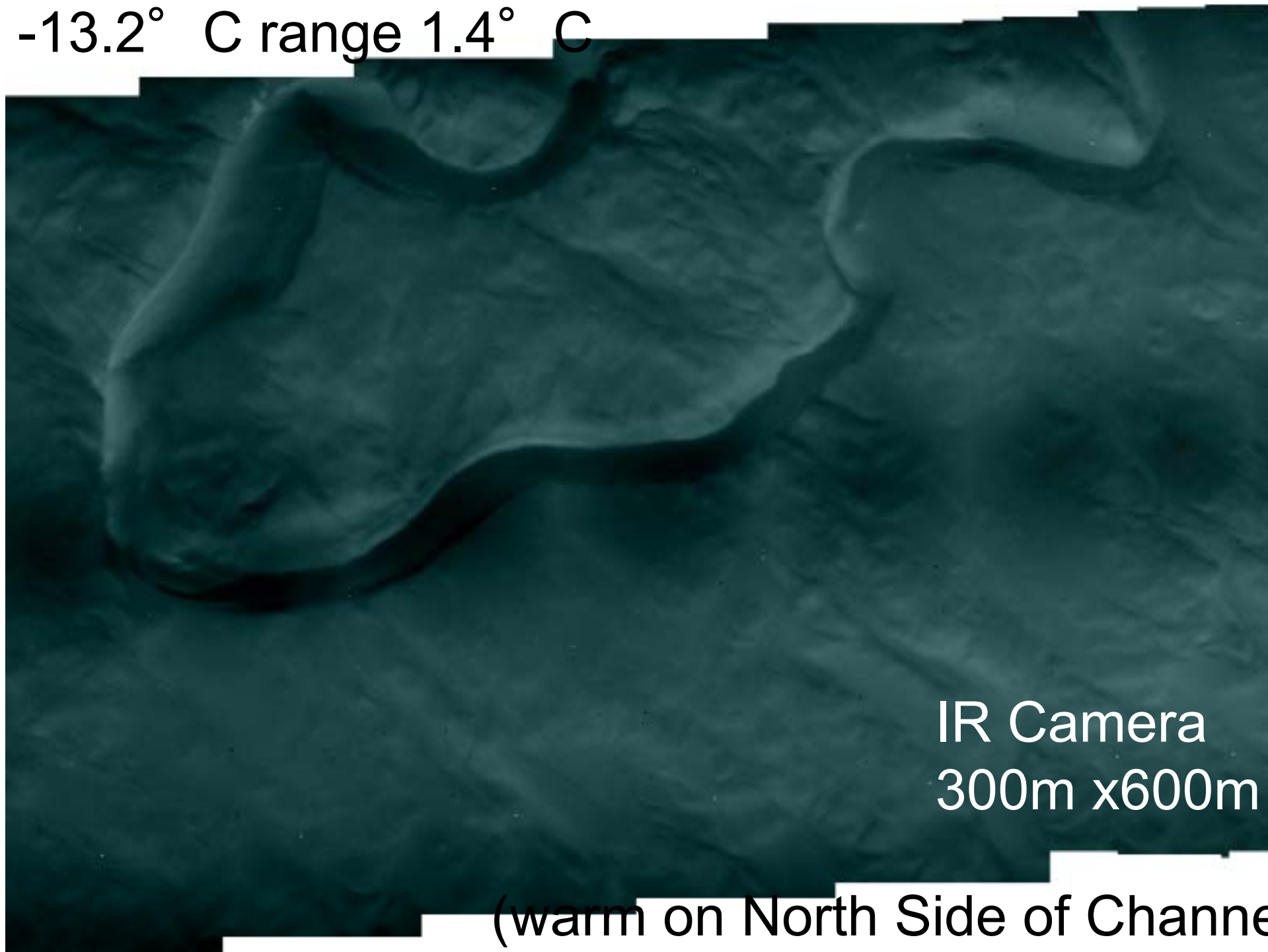






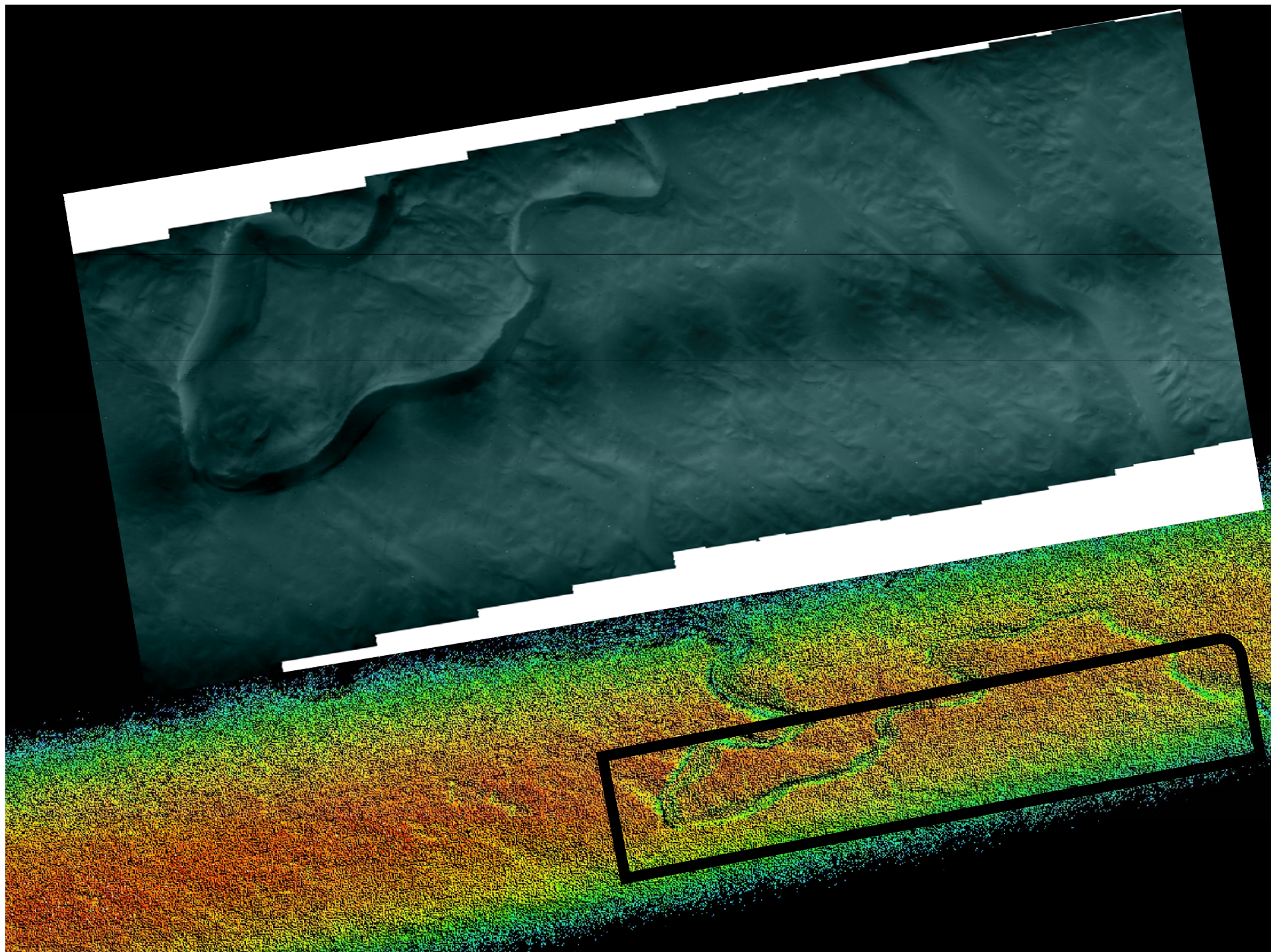
Team Icepod @ Raven August 2013

-13.2° C range 1.4° C



IR Camera
300m x600m

(warm on North Side of Channe

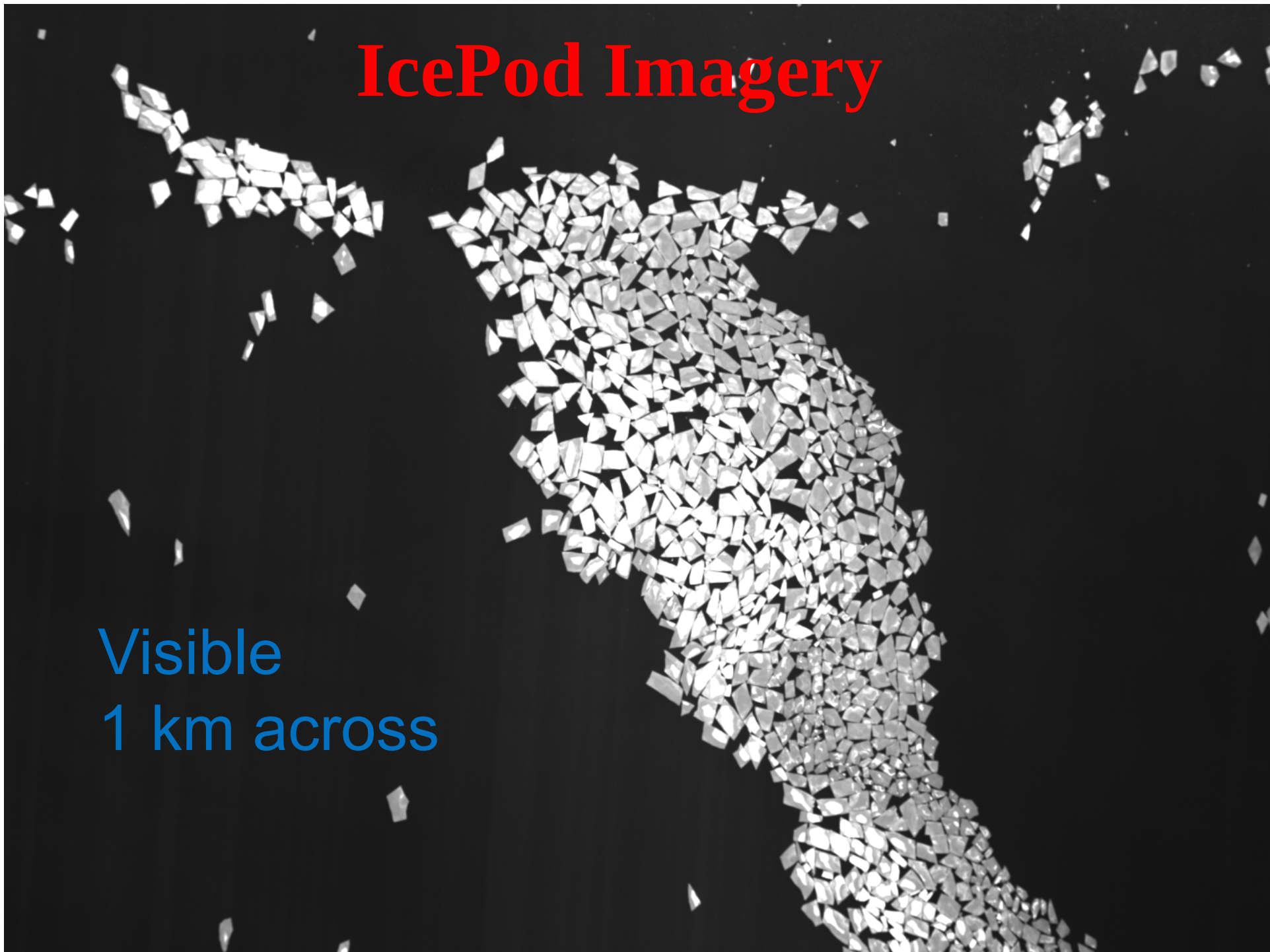




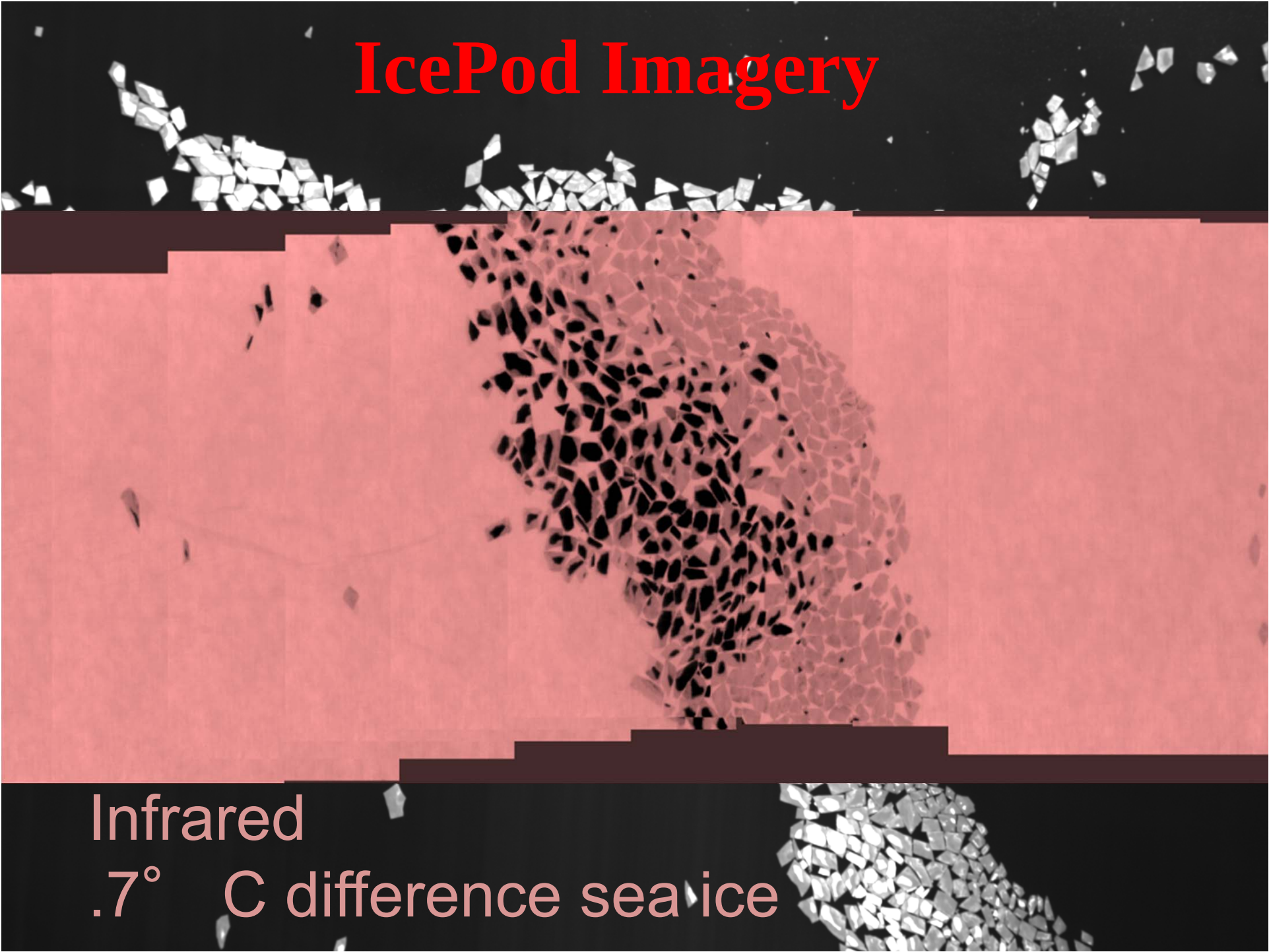


IcePod Imagery

Visible
1 km across

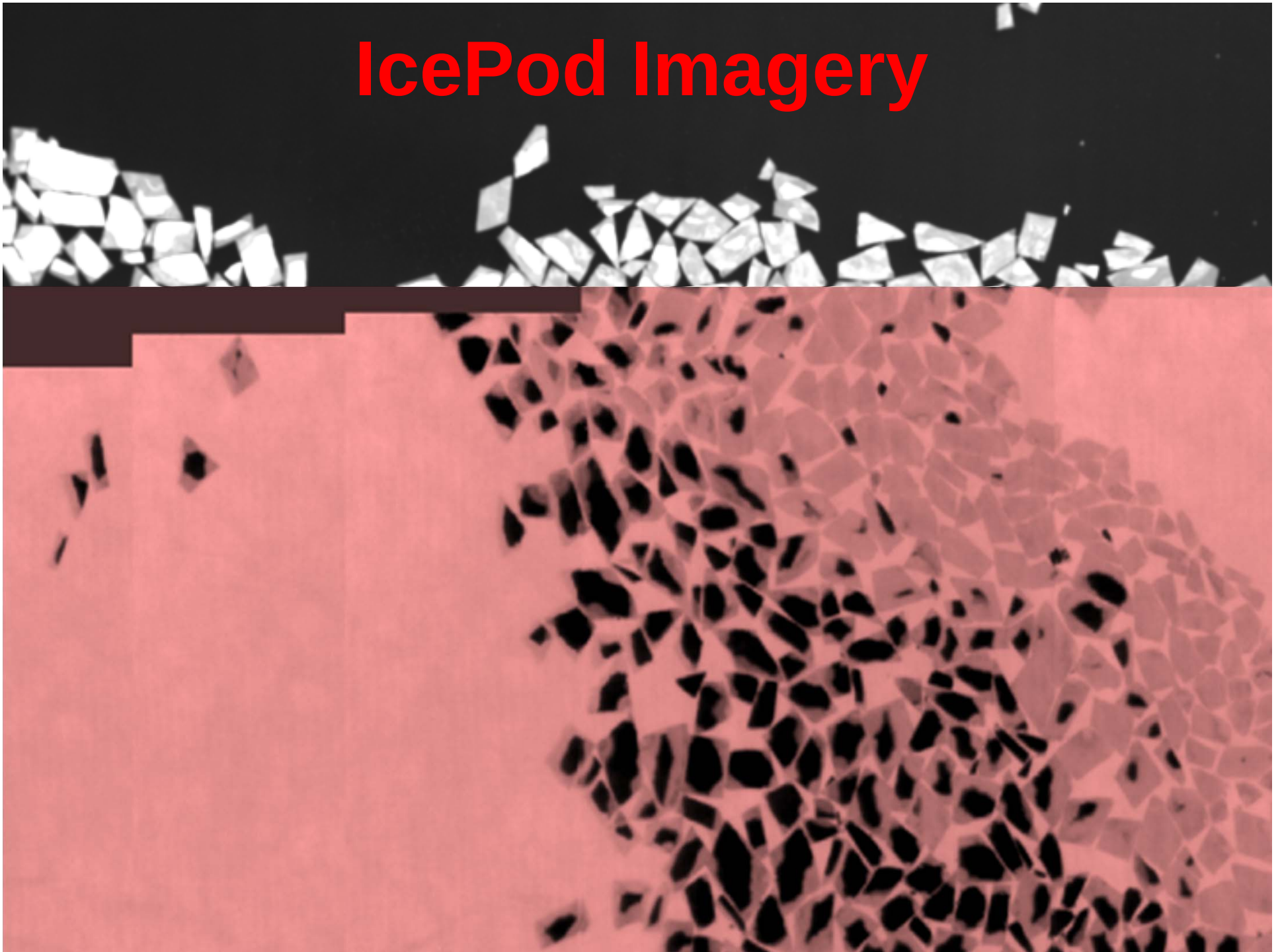


IcePod Imagery

The image displays a satellite view of sea ice. A large, irregularly shaped area of ice is highlighted with a semi-transparent red overlay, indicating a temperature difference of 0.7°C. This red area is surrounded by a black background, which represents the open ocean. The ice itself is depicted with a textured, crystalline appearance, showing various ice floes and leads. The red overlay is most prominent in the central and right portions of the ice field, while the left side shows more fragmented ice floes.

Infrared
.7° C difference sea ice

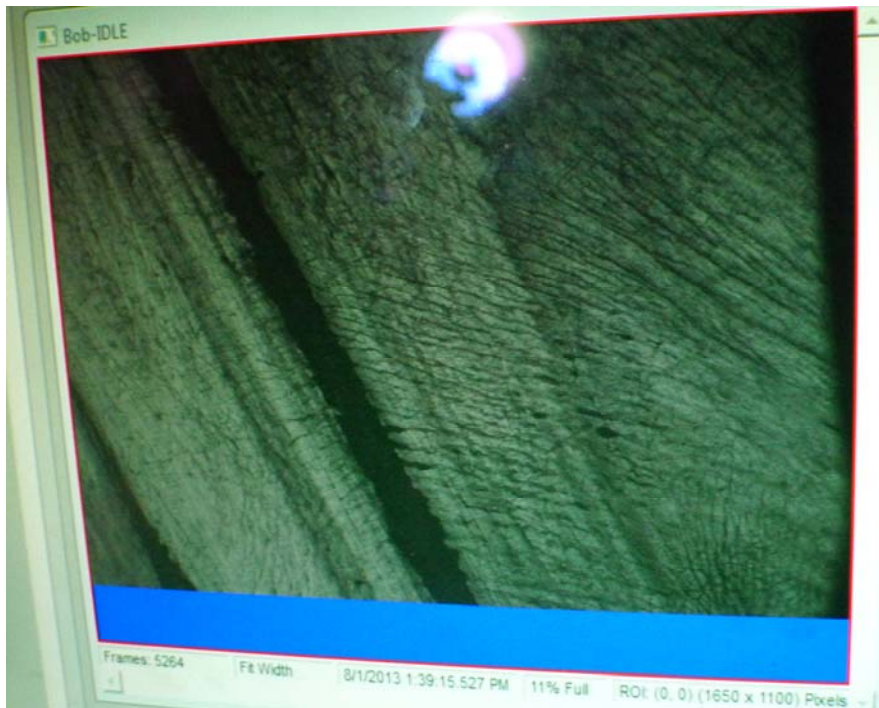
IcePod Imagery







Moraine Structure

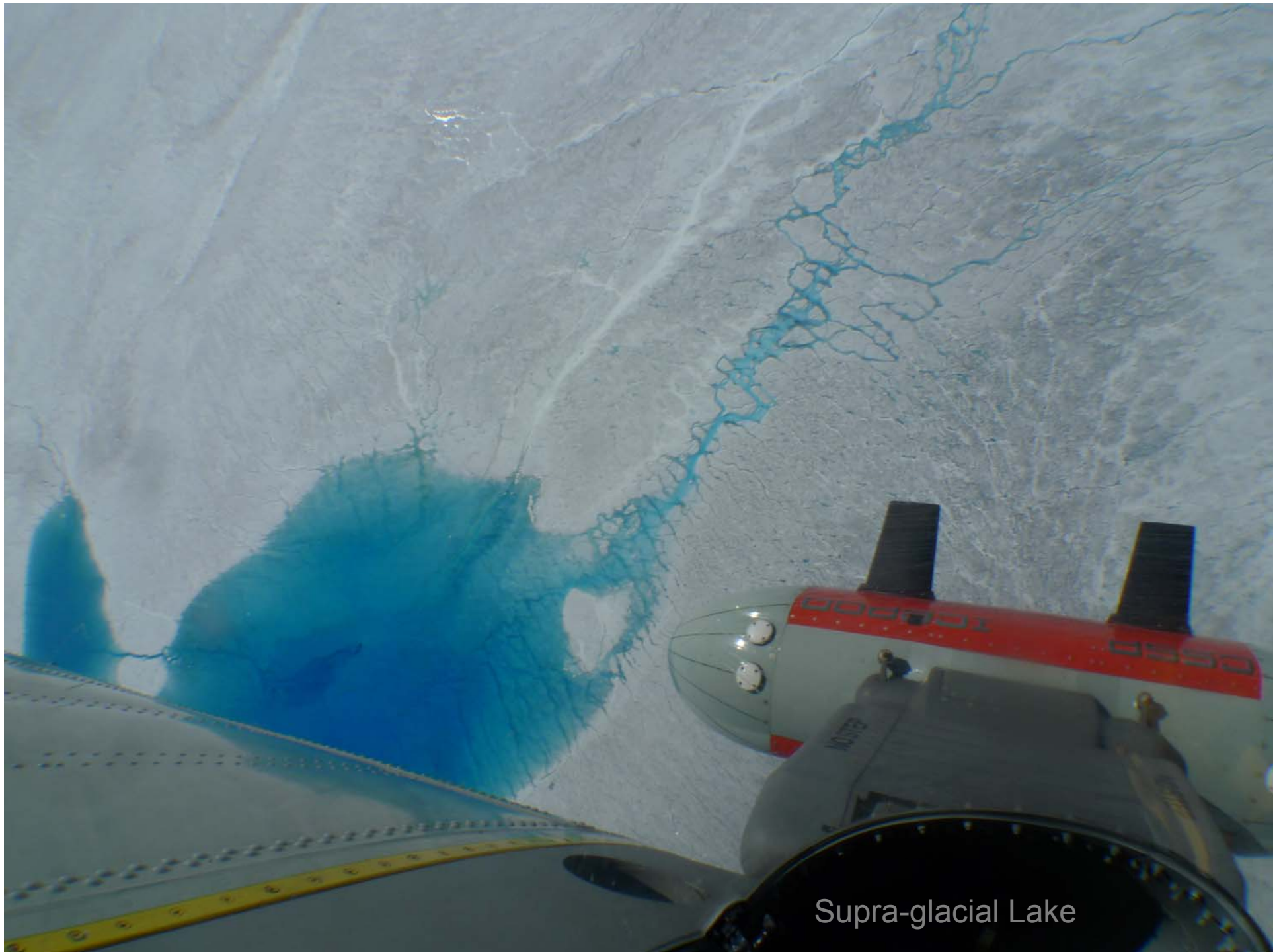


Visual
Moraine Structure



Thermal
Moraine Structure



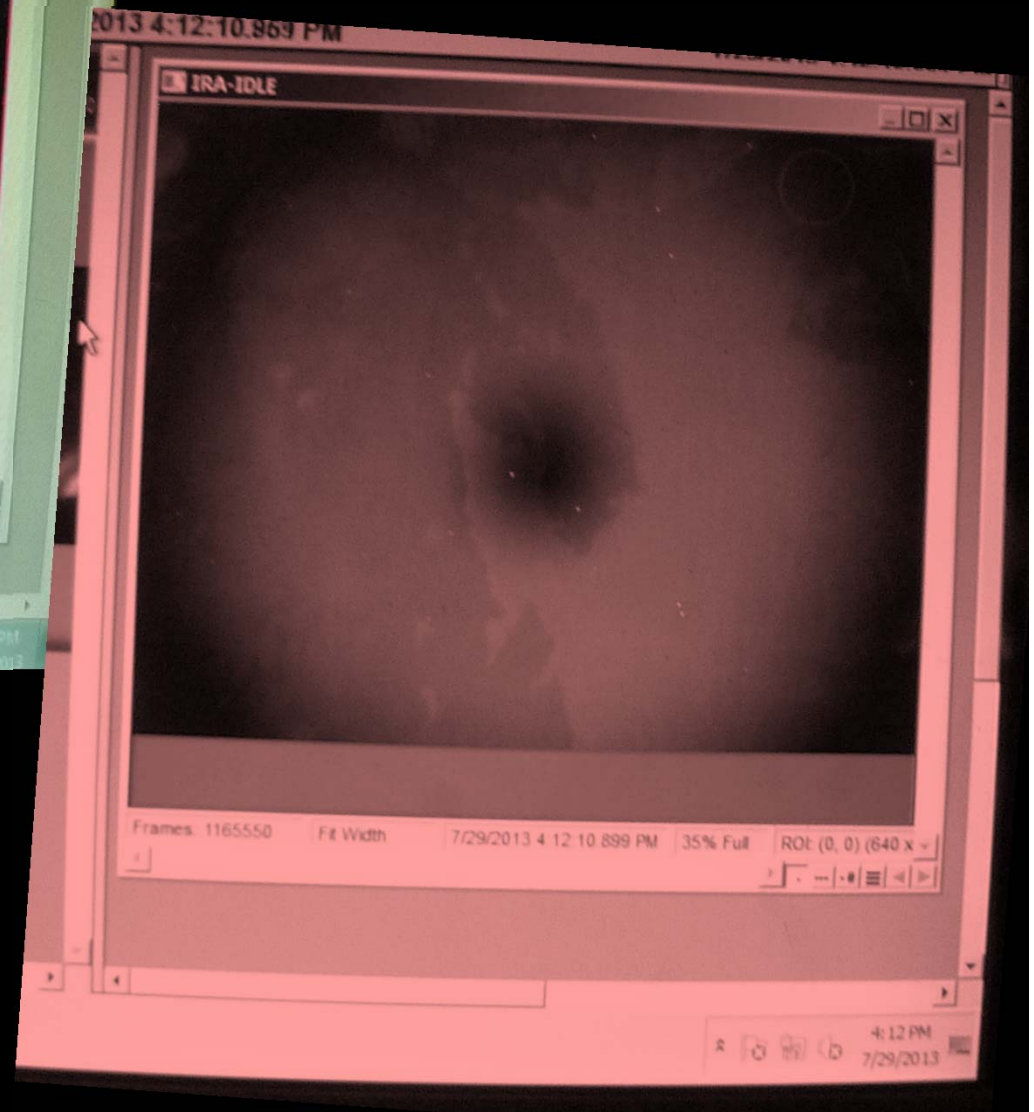


Supra-glacial Lake

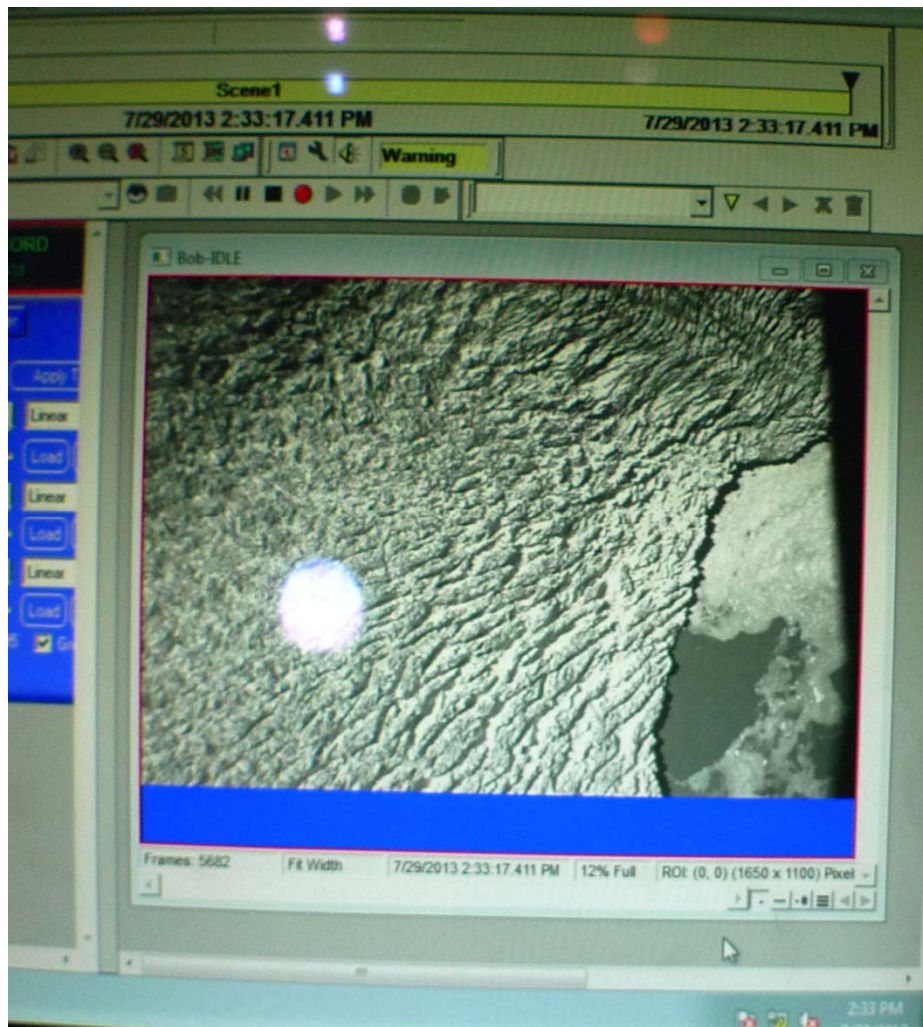


Visual
Supra-glacial Lake

Thermal
Supra-glacial Lake







Visual
Meltwater Plume

Thermal
Meltwater Plume





Capturing The Seasonal Melt Cycle

Piggyback Missions on NYANG Missions

April-August

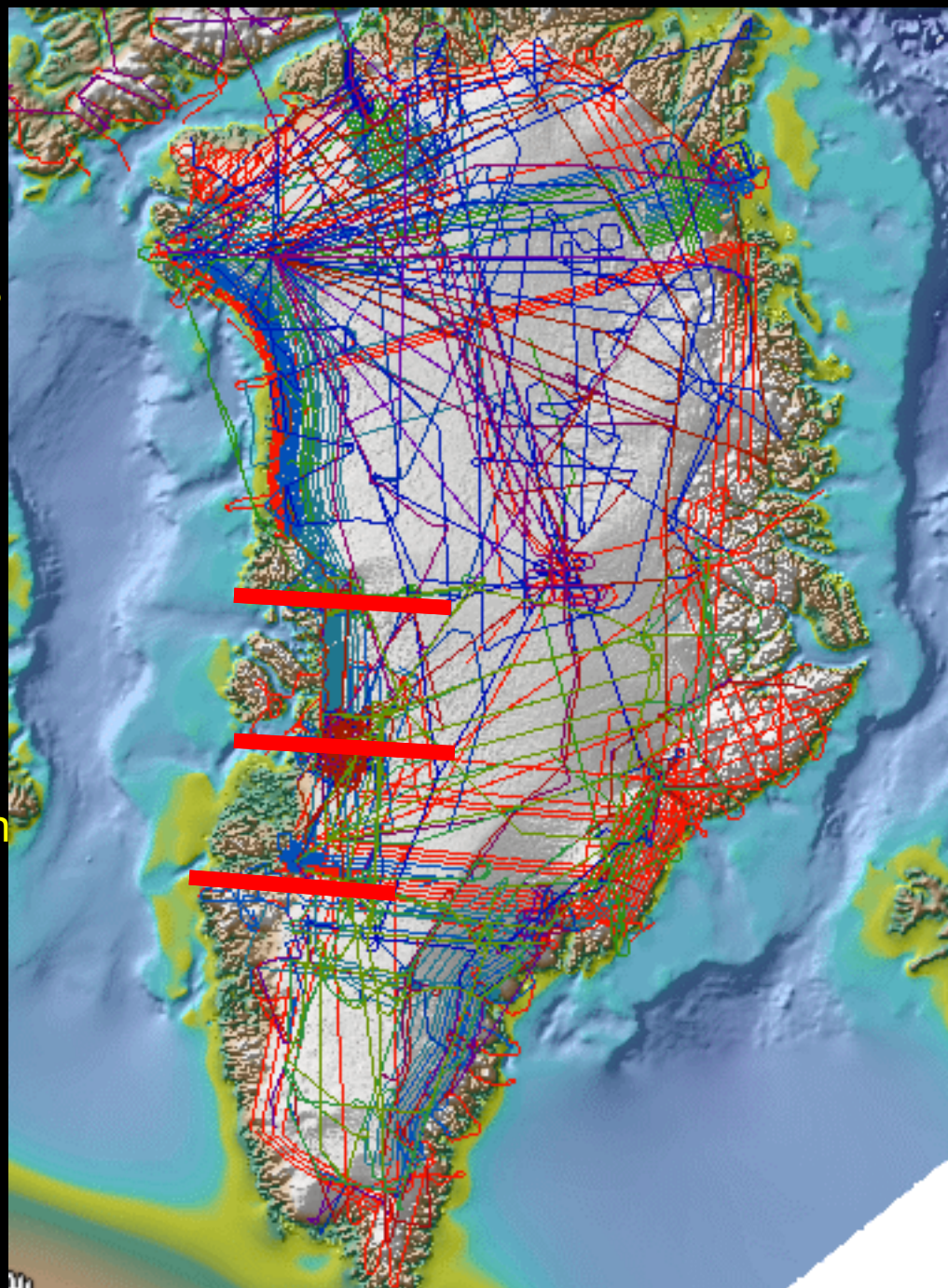
Benchmark Lines

Summit to the Coast (Rink??)

Jakobshavn

Russell Glacier – Return from Raven

Ice Surface Elevation
Surface Temperature
Surface Imagery
Shallow & Deep Radar
Plume Structure
Flow in Fjords
Deploy XCTD





Expanding Instrument Suite
Magnetometer
Gravity meter

Next Steps

Resolve Technical Issues

Demonstrate Data Products

Commission System in Antarctica (Suggestions)

Commission in Greenland

Develop Community Plan for Piggy Back Missions –
Greenland and Antarctica

Open Process for Dedicated Use Individual
Investigators

Develop Process New Instrumentation





